

Lecture 19: November 9

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[Lecture 19 video](#)

### 19.1 Outline

- Model Selection Problem
- Model Selection using Validation Data
- Model Selection using Training Data
- Bayesian Model Selection and Averaging

### 19.2 Model Selection Problem

We have a set of function classes  $\mathcal{G}_i \in \mathbb{R}^z, i \in \mathbb{N}$ , and

$$g_n^{(i)} = \operatorname{argmin}_{g \in \mathcal{G}_i} P_n g$$

$$P g_n^{(i)} \leq \inf_{g \in \mathcal{G}_i} P g + \operatorname{penalty}_i(n, \delta) \quad , \text{wp } 1 - \delta$$

$$P g_n = \min_i P g_n^{(i)}$$

We want to find the class such that the empirical performance is the best

$$g_n \in \operatorname{argmin}_{g \in \cup_i \mathcal{G}_i} P_n g$$

Note: If  $VC(\mathcal{G}_i) = d_i$ , then  $\operatorname{penalty}_i(n) = \sqrt{\frac{d_i \ln(\frac{1}{\delta})}{n}}$ .

### 19.3 Model Selection using Validation Data

We have  $z_{1:n}, z'_{1:m} \sim P^{\otimes(n+m)}$ , where  $z_{1:n}$  is the training data and  $z'_{1:m}$  is the validation data.

$$P'_m = \frac{1}{m} \sum_{i=1}^m \delta_{z'_i}$$

$$I = \operatorname{argmin}_{i \in \mathbb{N}} P'_m g_n^{(i)} + \sqrt{\ln \left( \frac{1}{q_i} \right)}$$

Here,  $\sqrt{\ln \left( \frac{1}{q_i} \right)}$  is the “complexity” penalty. Also,  $\sum q_i \leq 1, q_i \geq 0$ . A typical choice will be  $q_i = \frac{1}{i(i+1)}$  or  $q_i = \frac{1}{(i+1)^2}$ .

We want to consider less complex classes first (Occam’s razor) like  $d_1 \leq d_2 \leq \dots$  for VC classes.

**Theorem 19.1.** Let  $\sup_{z, z'} \sup_{g \in \cup_i \mathcal{G}_i} g(z) - g(z') \leq M$ , then

1. wp  $1 - \delta$ ,

$$Pg_n^I \leq \inf_{i \in \mathbb{N}} P'_m g_n^i + \sqrt{\ln \left( \frac{1}{q_i} \right)} + M \sqrt{\frac{\ln \left( \frac{1}{\delta} \right)}{2m}}$$

2. wp  $1 - \delta$ ,

$$Pg_n^I \leq \inf_{i \in \mathbb{N}} P g_n^i + \sqrt{\ln \left( \frac{1}{q_i} \right)} + M \sqrt{\frac{\ln \left( \frac{2}{\delta} \right)}{2m}}$$

## 19.4 Model Selection using Training Data

An alternative approach would be to use the training data for model selection instead of splitting.

$$(I, \mathcal{G}) := \operatorname{argmin} \{ P_n g + R_i(g, z_{1:n}) : i \in \mathbb{N}, g \in \mathcal{G}_i \}$$

Here,  $R_i(g, z_{1:n})$  is the data-dependent penalty.

**Theorem 19.2.**  $\sum q_i \leq 1, q_i \geq 0, \forall \delta \in (0, 1)$ ,

$$\alpha P_g \leq P_n g + \varepsilon_i(g, z_{1:n}) + \left( \frac{\ln \left( \frac{c_0}{\delta} \right)}{\lambda n} \right)^\beta$$

for some  $\alpha, \beta, \lambda > 0, c_0 \geq 1$ ,

$$R_i(g, z_{1:n}) \geq \varepsilon_i(g, z_{1:n}) + 2^{\max(0, \beta-1)} \left( \frac{\ln \left( \frac{c_0}{q_i} \right)}{\lambda n} \right)^\beta$$

Part 1:  $\forall \delta \in (0, 1)$  wp  $1 - \delta: \forall i \in \mathbb{N}, g \in \mathcal{G}$ ,

$$\alpha P_g \leq P_n g + R_i(g, z_{1:n}) + 2^{\max(0, \beta-1)} \left( \frac{\ln \left( \frac{c_0}{q_i} \right)}{\lambda n} \right)^\beta$$

Part 2:  $\forall \delta \in (0, 1), \forall i \in \mathbb{N}, g \in \mathcal{G}$ ,

$$P_n g + R_i(g, z_{1:n}) \leq \mathbb{E}[\alpha' P_n g + \alpha'' R_i(g, z_{1:n})] + \varepsilon'_i(g, \delta)$$

then wp  $1 - \delta$ ,

$$\alpha P G \leq \inf_{i \in \mathbb{N}, g \in \mathcal{G}_i} \left[ \alpha' P g + \alpha'' \mathbb{E}[R_i(g, z_{1:n})] + \varepsilon' \left( g, \frac{\delta}{2} \right) \right] + 2^{\max(0, \beta-1)} \left( \frac{\ln \left( \frac{c_0}{q_i} \right)}{\lambda n} \right)^\beta$$

### 19.4.1 Concentration of Empirical Rademacher Complexity

**Theorem 19.3.**

$$R_i(g, z_{1:n}) \geq 2R_n(\mathcal{G}_i, P) + M_i \sqrt{\frac{\ln\left(\frac{1}{q_i}\right)}{2n}}$$

where,  $M_i = \sup_{g \in \mathcal{G}_i} \sup_{z, z' \in \mathcal{Z}} g(z) - g(z')$ . Then,

1. *wp*  $1 - \delta$ :  $i \in \mathbb{N}, g \in \mathcal{G}_i$ ,

$$Pg \leq P_n g + R_i(g, z_{1:n}) + M_i \sqrt{\frac{\ln\left(\frac{1}{\delta}\right)}{2n}}$$

2. *wp*  $1 - \delta$ ,

$$PG \leq \inf_{i \in \mathbb{N}, g \in \mathcal{G}_i} P_n g + R_i(g, z_{1:n}) + 2M_i \sqrt{\frac{\ln\left(\frac{2}{\delta}\right)}{2n}}$$

**Theorem 19.4.**  $M \geq \sup_g \sup_{z, z'} g(z) - g(z')$ , then *wp*  $1 - \delta$ ,

$$R_n(\mathcal{G}, P) \leq R(\mathcal{G}, z_{1:n}) + M \sqrt{\frac{\ln\left(\frac{1}{\delta}\right)}{2n}}$$

Also *wp*  $1 - \delta$ ,

$$R_n(\mathcal{G}, P) \geq R(\mathcal{G}, z_{1:n}) - M \sqrt{\frac{\ln\left(\frac{1}{\delta}\right)}{2n}}$$

Here,  $R(\mathcal{G}, z_{1:n})$  is the empirical Rademacher complexity.

**Corollary 19.5.** *wp*  $1 - \delta$ :  $\forall g \in \mathcal{G}$ ,

$$Pg \leq P_n g + 2R(\mathcal{G}, z_{1:n}) + 3M \sqrt{\frac{\ln\left(\frac{2}{\delta}\right)}{2n}}$$

**Theorem 19.6.**

$$R_i(z_{1:n}) \geq R(\mathcal{G}_i, z_{1:n}) + 3M_i \sqrt{\frac{\ln\left(\frac{2}{q_i}\right)}{2n}}$$

Then,

1. *wp*  $1 - \delta$ :  $\forall i \in \mathbb{N}, g \in \mathcal{G}_i$ ,

$$Pg \leq P_n g + R_i(z_{1:n}) + 3M_i \sqrt{\frac{\ln\left(\frac{1}{\delta}\right)}{2n}}$$

2. *wp*  $1 - \delta$ ,

$$PG \leq \inf_{i \in \mathbb{N}, g \in \mathcal{G}_i} P_n g + \mathbb{E}[R_i(z_{1:n})] + 4M_i \sqrt{\frac{\ln\left(\frac{2}{\delta}\right)}{2n}}$$

## 19.5 Bayesian Model Selection and Averaging

Consider the Gibb's algorithm,

$$g \sim \exp(-\beta n P_n g) \pi_0(dg)$$

Here,  $g \in \mathcal{G}$  and  $\pi_0(dg)$  is the prior.

Take  $\sum q_i = 1$ ,

$$(I, \mathcal{G}) \sim P_i \pi_i(dg) \exp(-\beta n P_n g)$$

Here,  $\pi_i(dg)$  is the prior for class  $\mathcal{G}_i$ .

Now, we can use the Bayesian formula for Gibbs model selection and select a model randomly but in practice model averaging often leads to superior performance.

For  $f \in \mathcal{F} \subseteq \mathbb{R}^{\mathcal{X}}$ ,

$$\tilde{P}_n(df, i) = P_i \pi_i(dg) \exp(-\beta n P_n l(f))$$

Here,  $\tilde{P}_n(df, i)$  is the posterior.

Then we can make the predictions using,

$$\sum_i \int f(x) \tilde{P}_n(df, i)$$

*Claim:* Averaging >>> Any Model Selection